

INSTRUCTION MANUAL



Model 014A Met One Wind Speed Sensor

Revision: 2/17



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General

- Prior to performing site or installation work, obtain required approvals and permits. Comply with all governing structure-height regulations, such as those of the FAA in the USA.
- Use only qualified personnel for installation, use, and maintenance of tripods and towers, and any attachments to tripods and towers. The use of licensed and qualified contractors is highly recommended.
- Read all applicable instructions carefully and understand procedures thoroughly before beginning work.
- Wear a **hardhat** and **eye protection**, and take **other appropriate safety precautions** while working on or around tripods and towers.
- **Do not climb** tripods or towers at any time, and prohibit climbing by other persons. Take reasonable precautions to secure tripod and tower sites from trespassers.
- Use only manufacturer recommended parts, materials, and tools.

Utility and Electrical

- **You can be killed** or sustain serious bodily injury if the tripod, tower, or attachments you are installing, constructing, using, or maintaining, or a tool, stake, or anchor, come in **contact with overhead or underground utility lines**.
- Maintain a distance of at least one-and-one-half times structure height, 20 feet, or the distance required by applicable law, **whichever is greater**, between overhead utility lines and the structure (tripod, tower, attachments, or tools).
- Prior to performing site or installation work, inform all utility companies and have all underground utilities marked.
- Comply with all electrical codes. Electrical equipment and related grounding devices should be installed by a licensed and qualified electrician.

Elevated Work and Weather

- Exercise extreme caution when performing elevated work.
- Use appropriate equipment and safety practices.
- During installation and maintenance, keep tower and tripod sites clear of un-trained or non-essential personnel. Take precautions to prevent elevated tools and objects from dropping.
- Do not perform any work in inclement weather, including wind, rain, snow, lightning, etc.

Maintenance

- Periodically (at least yearly) check for wear and damage, including corrosion, stress cracks, frayed cables, loose cable clamps, cable tightness, etc. and take necessary corrective actions.
- Periodically (at least yearly) check electrical ground connections.

WHILE EVERY ATTEMPT IS MADE TO EMBODY THE HIGHEST DEGREE OF SAFETY IN ALL CAMPBELL SCIENTIFIC PRODUCTS, THE CUSTOMER ASSUMES ALL RISK FROM ANY INJURY RESULTING FROM IMPROPER INSTALLATION, USE, OR MAINTENANCE OF TRIPODS, TOWERS, OR ATTACHMENTS TO TRIPODS AND TOWERS SUCH AS SENSORS, CROSSARMS, ENCLOSURES, ANTENNAS, ETC.

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Met One 014A Wind Speed Sensor

1. Introduction

The 014A is a three-cup anemometer that monitors horizontal wind speed for the range of 0 to 45 m s⁻¹ with a threshold of 0.45 m s⁻¹. It connects directly to a Campbell Scientific datalogger, which measures the 014A's pulse signal and converts the signal to engineering units (mph, m s⁻¹, knots).

NOTE

This manual provides information only for CRBasic dataloggers. It is also compatible with most of our retired Edlog dataloggers. For Edlog datalogger support, see an older manual at www.campbellsci.com/old-manuals.

2. Precautions

- READ AND UNDERSTAND the *Safety* section at the front of this manual.
- Caution – The black outer jacket of the cable is Santoprene® rubber. This compound is resistant to temperature extremes, moisture, and UV degradation. However, this cable jacket will support combustion in air. It is rated as slow burning when tested according to U.L. 94 H.B. and will pass FMVSS302. Local fire codes may preclude its use inside buildings.
- Caution – Although the 014A is rugged, it should be handled as a precision scientific instrument.

3. Initial Inspection

- Upon receipt of the 014A, inspect the packaging and contents for damage. File damage claims with the shipping company.
- Refer to Section 3.1, *Ships With (p. 1)*, to ensure that all parts are included.

3.1 Ships With

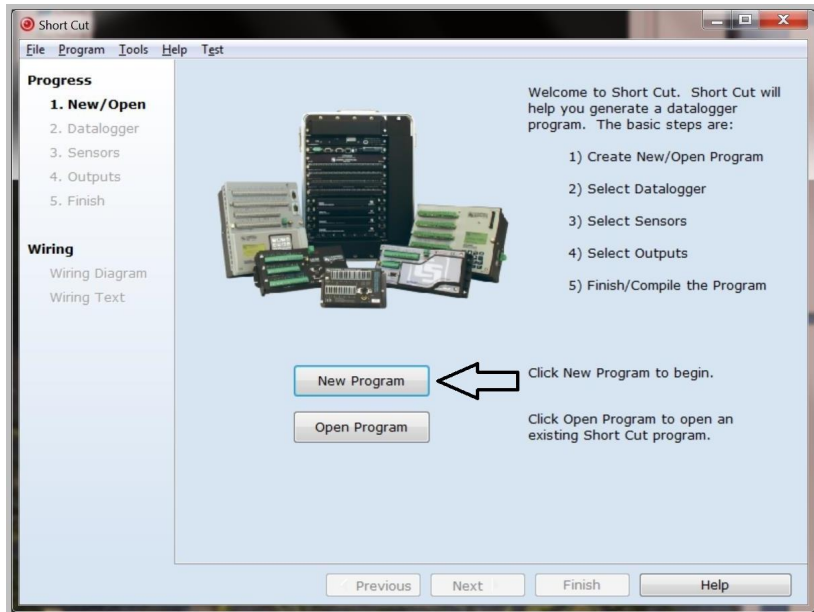
- (1) 5/64-inch Allen Wrench
- (1) Calibration Sheet
- (1) 014ACBL-L Sensor Cable with user-specified length
- (1) *ResourceDVD* or Instruction Manual

4. QuickStart

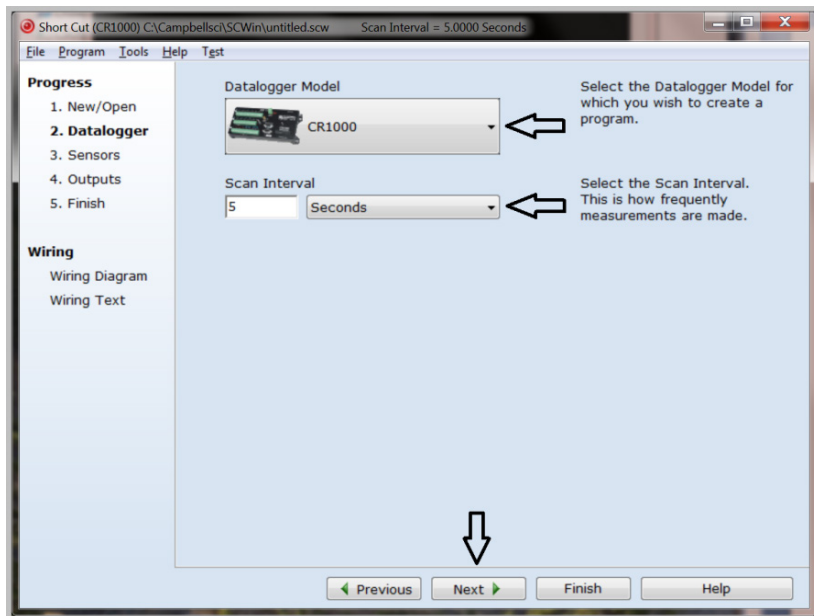
Short Cut is an easy way to program your datalogger to measure the 014A and assign datalogger wiring terminals. *Short Cut* is available as a download on www.campbellsci.com and the *ResourceDVD*. It is included in installations of *LoggerNet*, *PC200W*, *PC400*, or *RTDAQ*.


The following procedure shows using *Short Cut* to program the 014A.

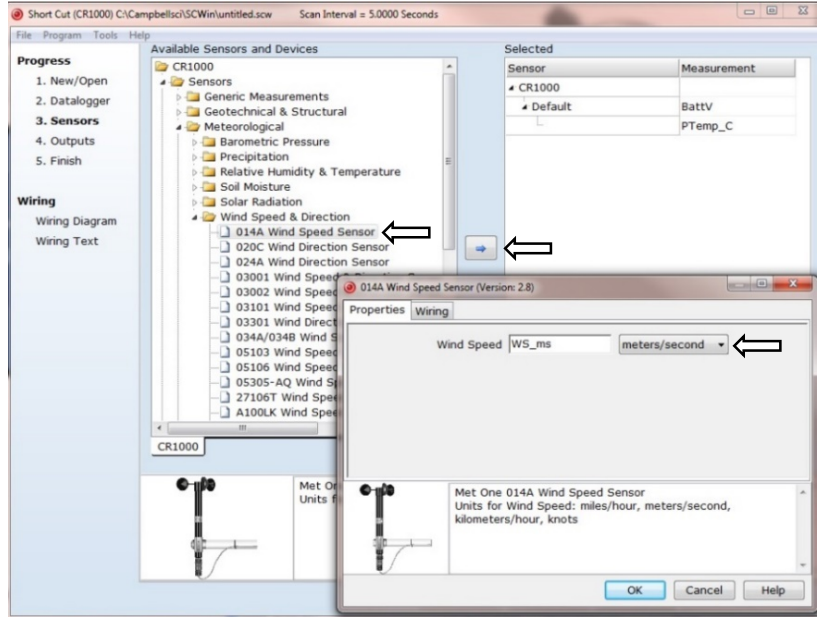
1. Open *Short Cut*. Click **New Program**.



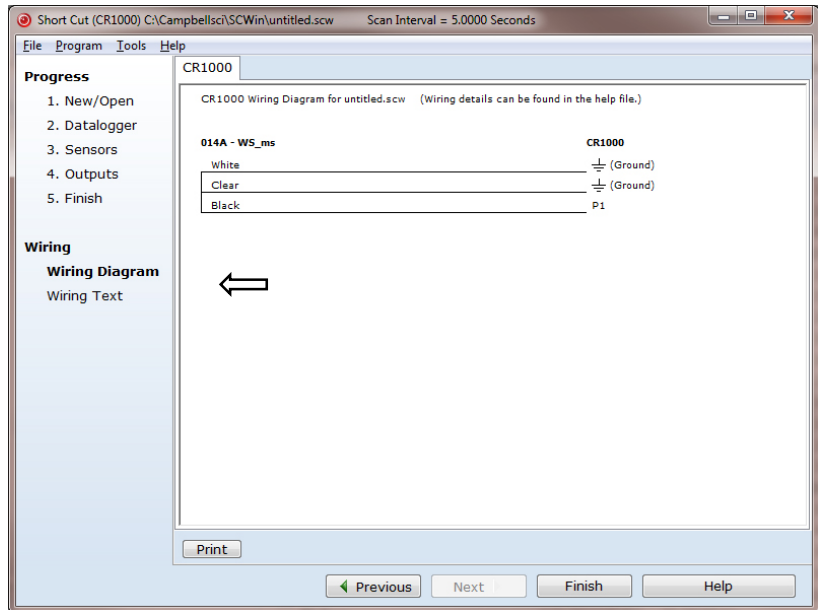
2. Select **Datalogger Model** and **Scan Interval** (default of 5 seconds is OK for most applications). Click **Next**.



- Under the **Available Sensors and Devices** list, select the **Sensors | Meteorological | Wind Speed & Direction** folder. Select **014A Wind Speed Sensor**. Click  to move the selection to the **Selected** device window. The wind speed defaults to meters/second. This can be changed by clicking the **Wind Speed** box and selecting one of the other options.



- After selecting the sensor, click **Wiring Diagram** to see how the sensor is to be wired to the datalogger. The wiring diagram can be printed now or after more sensors are added.



5. Select any other sensors you have, then finish the remaining *Short Cut* steps to complete the program. The remaining steps are outlined in *Short Cut Help*, which is accessed by clicking on **Help | Contents | Programming Steps**.
6. If *LoggerNet*, *PC400*, *RTDAQ*, or *PC200W* is running on your PC, and the PC to datalogger connection is active, you can click **Finish** in *Short Cut* and you will be prompted to send the program just created to the datalogger.
7. If the sensor is connected to the datalogger, as shown in the wiring diagram in step 4, check the output of the sensor in the datalogger support software data display to make sure it is making reasonable measurements.

5. Overview

The 014A is constructed of corrosion-resistant, stainless-steel and anodized aluminum. Its three-cup anemometer assembly contains a sealed magnetic reed switch. Rotation of the cup wheel produces a pulse that is directly proportional to wind speed.

The accompanying Met One manual contains additional information on operating principals, installation, and maintenance.

The -L portion of the model number indicates that the 014A has a user-specified cable length. TABLE 5-1 gives the recommended lead length for mounting the sensor at the top of the tripod/tower with a CM202 crossarm.

TABLE 5-1. Recommended Lead Lengths						
CM106B	CM110	CM115	CM120	UT10	UT20	UT30
14 ft	14 ft	19 ft	24 ft	14 ft	24 ft	37 ft

The 014A's cables can terminate in:

- Pigtails that connect directly to a Campbell Scientific datalogger (cable termination option -PT).
- Connector that attaches to a prewired enclosure (cable termination option -PW).

6. Specifications

Features:

- Ideal for applications that do not require wind direction measurements
- Sealed magnetic reed switch
- Designed for continuous, long term, unattended operation in adverse conditions
- Compatible with Campbell Scientific CRBasic dataloggers: CR200(X) series, CR300 series, CR6 series, CR800 series, CR1000, CR3000, CR5000, and CR9000(X)

Threshold:	0.45 m s ⁻¹ (1 mph)
Calibrated Range:	0 to 45 m s ⁻¹ (0 to 100 mph)
Gust Survival:	0 to 53 m s ⁻¹ (0 to 120 mph)
Accuracy:	1.5% or 0.11 m s ⁻¹ (0.25 mph)
Temperature Range:	-50 to 70 °C
Output Signal:	Contact Closure, Reed Switch
Weight:	680 g (1.5 lb)

6.1 Distance Constant*

Standard:	Less than 4.6 m (15 ft) (Aluminum Cups)
Optional Fast Response:	Less than 1.5 m (5 ft) (Lexan Cups)

* The distance traveled by the air after a sharp-edged gust has occurred for the anemometer to reach 63% of the new speed.

7. Installation

If you are programming your datalogger with *Short Cut*, skip Section 7.3, *Wiring* (p. 9), and Section 7.4, *Programming* (p. 9). *Short Cut* does this work for you. See Section 4, *QuickStart* (p. 1), for a *Short Cut* tutorial.

7.1 Siting

Locate wind sensors away from obstructions (for example, trees and buildings). As a general rule, there should be a horizontal distance of at least ten times the height of the obstruction between the sensor and the obstruction. If it is necessary to mount the sensors on the roof of a building, the height of the sensors, above the roof, should be at least 1.5 times the height of the building. See Section 10, *References* (p. 11), for a list of references that discuss siting wind speed and direction sensors.

7.2 Assemble and Mount the Sensor

7.2.1 Tools Required

- 5/64-inch Allen wrench (shipped with the 014A)
- 1/2-inch open end wrench
- compass and declination angle for the site
- small screw driver provided with datalogger
- UV resistant cable ties
- small pair of diagonal-cutting pliers
- 6-inch to 10-inch torpedo level

7.2.2 Assemble the Sensor

The 014A ships with the cup assembly separate from the main housing. Assemble the sensor using the following procedure:

1. Take the cup assembly and main housing out of the shipping box (see FIGURE 7-1).



FIGURE 7-1. 014A shipping box

2. Gently slide the cup assembly down over the shaft at the top of the sensor until it meets the top bearing.
3. Use the 5/64-inch Allen wrench to tighten the screw on the side of the cup assembly; tighten until snug (see FIGURE 7-2).



FIGURE 7-2. Allen wrench tightening bolt

4. Ensure that the cup assembly spins freely.

7.2.3 Mounting to a Crossarm

The 014A mounts to a crossarm using a 3/4 x 1-inch Nu-Rail Crossover Fitting (pn 1049) or a CM220 Right-Angle Mounting Kit.

1. Mount a CM200-series crossarm to the tripod or tower.
2. Orient the crossarm North-South, with the CM220 (FIGURE 7-4) or 1049 Nu-Rail (FIGURE 7-3) on the north end.
3. Insert the base of the 014A into the Nu-Rail or CM220 U-bolt (FIGURES 7-3 and 7-4) and tighten the set screws on the Nu-Rail, or U-bolt on the CM220 (do not over tighten).
4. Attach the sensor cable to the connector on the 014A. Make sure the connector is properly keyed, and finger-tighten the knurled ring.
5. Route the sensor cable along the underside of the crossarm to the tripod/tower, and to the instrument enclosure.
6. Secure the cable to the crossarm and tripod/tower using cable ties.

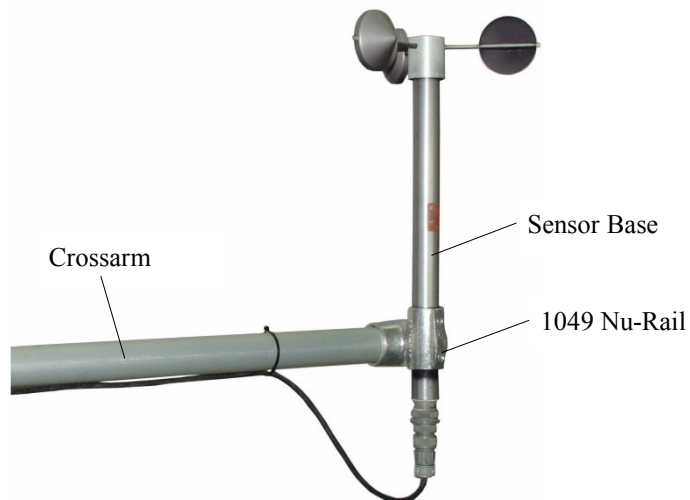


FIGURE 7-3. 014A mounted on a crossarm with pn 1049

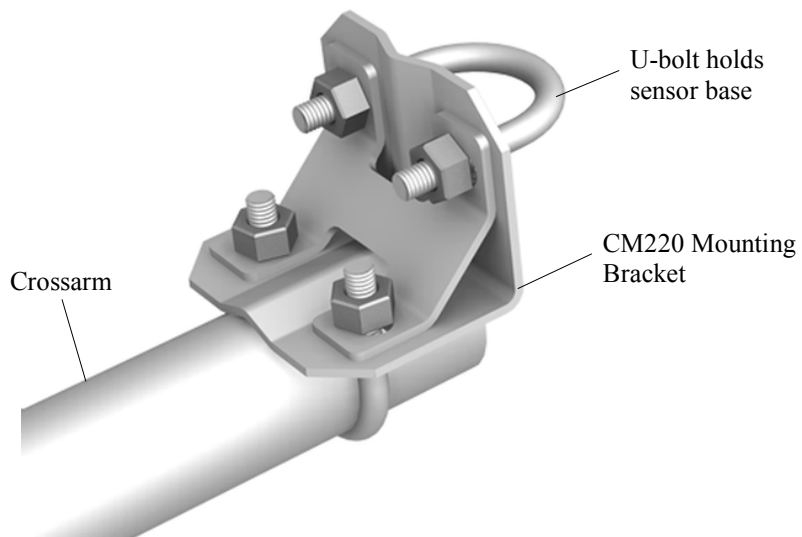


FIGURE 7-4. CM220 Right Angle Mounting Bracket

7.2.4 Mounting on Top of a Tripod

The 014A can be attached to the top of a CM106B, CM110, CM115, or CM120 tripod via the CM216 Sensor Mounting Kit. The CM216 extends 10 cm (4 in) above the mast of the tripod.



7.3 Wiring

Connections to our dataloggers are provided in TABLE 7-1. The sensor is typically measured with a pulse channel. Many dataloggers can also use a control port to measure the 014A. With this option, the white wire is connected to the 5V terminal.

TABLE 7-1. Wire Color, Wire Function, and Datalogger Connection

Wire Color	Wire Function	Pulse Input Datalogger Connection Terminal	Control Port Datalogger Connection Terminal
Black	Signal	U configured for pulse input ¹ , P (pulse input), or P_SW (pulse, switch closure input)	C (control port)
White	Signal Reference	⏏	5V
Clear	Shield	AG or ⏏ (analog ground)	AG or ⏏ (analog ground)

¹U channels are automatically configured by the measurement instruction.

7.4 Programming

Short Cut is the best source for up-to-date datalogger programming code. Programming code is needed when:

- Creating a program for a new datalogger installation.
- Adding sensors to an existing datalogger program.

If your data acquisition requirements are simple and you are connecting the sensor to a pulse port, you can probably create and maintain a datalogger program exclusively with *Short Cut*. If your data acquisition needs are more complex, the files that *Short Cut* creates are a great source for programming code to start a new program or add to an existing custom program.

NOTE *Short Cut* cannot edit programs after they are imported and edited in *CRBasic Editor*.

A *Short Cut* tutorial is available in Section 4, *QuickStart* (p. 1). If you wish to import *Short Cut* code into *CRBasic Editor* to create or add to a customized program, follow the procedure in Appendix A, *Importing Short Cut Code Into CRBasic Editor* (p. A-1). Programming basics for CRBasic dataloggers are provided in the following sections. Complete program examples for select CRBasic dataloggers can be found in Appendix B, *Example Programs* (p. B-1). Programming basics and programming examples for Edlog dataloggers are provided at www.campbellsci.com/old-manuals.

7.4.1 Wind Speed

Typically, the sensor is connected to a pulse channel and measured with the **PulseCount()** instruction, using the Switch Closure configuration and set to output frequency in Hertz (Appendix B.1, *Pulse Example Program* (p. B-1)).

The **TimerIO()** CRBasic instruction is used when the sensor is connected to a control port (Appendix B.2, *Control Port Example Program* (p. B-2)).

The expression for wind speed (U) is:

$$U = MX + B$$

where

M = multiplier

X = number of pulses per second (hertz)

B = offset

TABLE 7-2 lists the multipliers (M) and offsets (Off) to obtain meters/second or miles/hour when the pulse count instruction is configured to output the result in Hz.

TABLE 7-2. Wind Speed Multiplier*		
Model	Meters/Second	Miles/Hour
014A	M = 0.8000 Off = 0.447	M = 1.789 Off = 1.0
*When configured to output counts, the above multiplier is divided by the execution interval in seconds		

8. Maintenance

8.1 Suggested Maintenance Schedules

8.1.1 6 to 12 Month Periodic Service

Visually inspect the anemometer cups for cracks and breaks, and make sure that each arm is securely attached to the cup assembly hub. Also check to see that the vent hole, located at the base of the sensor, is unobstructed.

Special caution is advised under adverse conditions of high winds, heat, and/or sandy areas. Look for abrupt stopping of the cup assembly with slow cup rotation. If this occurs, the bearings may need to be replaced.

8.1.2 12 to 24 Month Service

Replace sensor bearings.

8.1.3 24 to 36 Month Service

A complete factory overhaul of the sensor is recommended. Contact Met One directly for wind speed sensor repair and recalibration service. This repair and calibration service includes disassembly and detailed inspection of all moving mechanical parts and all electronic components. Service includes replacement of bearings, shaft, and set screws as well as a functional test of the sensor. Charges above the basic service charge may be added for replacement of additional materials.

Met One Instruments, Inc.
1600 Washington Blvd.
Grants Pass, OR 97526
(541) 471-7111
FAX (541) 471-7116

9. Troubleshooting

Symptom: No wind speed

1. Check that the sensor is wired to the pulse channel specified by the pulse count instruction.
2. Disconnect the sensor from the datalogger and use an ohm meter to check the reed switch. The resistance between the white and black wires should vary from infinite (switch open) to less than 1 ohm (switch closed) as the cup wheel is slowly turned.
3. Verify that the Configuration Code (switch closure, hertz), and multiplier and offset parameters for the pulse count instruction are correct for the datalogger type.

10. References

The following references give detailed information on siting wind speed and wind direction sensors.

EPA, 1989: *Quality Assurance Handbook for Air Pollution Measurements System*, Office of Research and Development, Research Triangle Park, NC, 27711.

EPA, 1987: *On-Site Meteorological Program Guidance for Regulatory Modeling Applications*, EPA-450/4-87-013, Office of Air Quality Planning and Standards, Research Triangle Park, NC 27711.

The State Climatologist, 1985: *Publication of the American Association of State Climatologists: Height and Exposure Standards*, for Sensors on Automated Weather Stations, vol. 9, No. 4.

WMO, 1983: *Guide to Meteorological Instruments and Methods of Observation*, World Meteorological Organization, No. 8, 5th edition, Geneva, Switzerland.

Appendix A. Importing Short Cut Code Into CRBasic Editor

This tutorial shows:

- How to import a *Short Cut* program into a program editor for additional refinement
- How to import a wiring diagram from *Short Cut* into the comments of a custom program

Short Cut creates files, which can be imported into *CRBasic Editor*. Assuming defaults were used when *Short Cut* was installed, these files reside in the C:\campbellsci\SCWin folder:

- .DEF (wiring and memory usage information)
- .CR2 (CR200(X)-series datalogger code)
- .CR300 (CR300-series datalogger code)
- .CR6 (CR6-series datalogger code)
- .CR8 (CR800-series datalogger code)
- .CR1 (CR1000 datalogger code)
- .CR3 (CR3000 datalogger code)
- .CR5 (CR5000 datalogger code)
- .CR9 (CR9000(X) datalogger code)

Use the following procedure to import *Short Cut* code and wiring diagram into *CRBasic Editor*.

1. Create the *Short Cut* program following the procedure in Section 4, *QuickStart* (p. 1). Finish the program and exit *Short Cut*. Make note of the file name used when saving the *Short Cut* program.
2. Open *CRBasic Editor*.
3. Click **File | Open**. Assuming the default paths were used when *Short Cut* was installed, navigate to C:\CampbellSci\SCWin folder. The file of interest has the .CR2, .CR300, .CR6, .CR8, .CR1, .CR3, .CR5, or .CR9 extension. Select the file and click **Open**.
4. Immediately save the file in a folder different from C:\Campbellsci\SCWin, or save the file with a different file name.

NOTE

Once the file is edited with *CRBasic Editor*, *Short Cut* can no longer be used to edit the datalogger program. Change the name of the program file or move it, or *Short Cut* may overwrite it next time it is used.

5. The program can now be edited, saved, and sent to the datalogger.
6. Import wiring information to the program by opening the associated .DEF file. Copy and paste the section beginning with heading “-Wiring for CRXXX-” into the CRBasic program, usually at the head of the file. After pasting, edit the information such that an apostrophe (') begins each line. This character instructs the datalogger compiler to ignore the line when compiling.

Appendix B. Example Programs

B.1 Pulse Example Program

The following CR1000 program uses a pulse port to measure the 014A every 5 seconds. The programs store mean wind speed (in m s^{-1}) every 60 minutes. Wiring for the examples is given in TABLE B-1.

Color	Description	CR1000
Black	Signal	P1
White	Signal Reference	\perp
Clear	Shield	\perp

CRBasic Example B-1. CR1000 Program Measuring 014A Using Pulse Channel

```
'CR1000

'Declare Variables and Units
Public Batt_Volt
Public WS_ms

Units Batt_Volt=Volts
Units WS_ms=meters/second

'Define Data Tables
DataTable(Table1,True,-1)
  DataInterval(0,60,Min,10)
  Average(1,WS_ms,FP2,False)
EndTable

'Main Program
BeginProg
  Scan(5,Sec,1,0)
    'Default Datalogger Battery Voltage measurement Batt_Volt:
    Battery(Batt_Volt)
    '014A Wind Speed Sensor measurement WS_ms:
    PulseCount(WS_ms,1,1,2,1,0.8,0.447)
    If WS_ms<0.448 Then WS_ms=0
    'Call Data Tables and Store Data
    CallTable(Table1)
  NextScan
EndProg
```

B.2 Control Port Example Program

The following CR3000 program uses control ports to measure three 014A wind speed sensor. The program measures them every second and stores the mean wind speed (in m s^{-1}) every 15 seconds.

CRBasic Example B-2. CR3000 Program Measuring 014A Using Control Port

```
'CR3000

'Declare Variables and Units
Public J, WindSpeed(3)

'Define data table
DataTable (WindTab,True,-1)
    DataInterval (0,15,Sec,10)
    Average (3,WindSpeed(),IEEE4,False)
EndTable

'Main Program
BeginProg
    Scan (1,Sec,3,0)
        'Measure WindSpeed Profile 014A, 3 anemometers connected to C1, C2, C3
        TimerIO (WindSpeed(),11111000,00000222,100,mSec)

        For J = 1 To 3
            'Convert measurement to windspeed m/s
            WindSpeed(j) = 0.447 + WindSpeed(j)/1.25
        Next j
        CallTable (WindTab)
    NextScan
EndProg
```


Appendix C. Sensor Maintenance

C.1 Reed Switch Replacement Procedure

To verify parts and locations, refer to the cable and parts diagrams (FIGURE C-2 and FIGURE C-3) and the parts list (TABLE C-1).

- A. Remove sensor from mounting arm and disconnect cable.
- B. Remove the cup assembly.
- C. Remove the three Philips screws at the top of the sensor and lift out the bearing mount assembly.
- D. Unsolder the leads of the reed switch and remove the switch from the two mounting terminals, see the parts diagram.
- E. Solder the new switch onto the sides of the switch mount terminals (form a loop in the relay leads to obtain proper lead length — **DO NOT CUT THE RELAY LEADS**). Measure the distance between the bottom of the rotating magnet and the top of the switch envelope, as shown in FIGURE C-1. The spacing should measure between 0.01 and 0.02 inches.
- F. Spin the shaft to verify switch operation by listening for a faint sound of the switch closure. If the switch cannot be heard, move the switch slightly closer to the magnet assembly.
- G. Reassemble sensor.

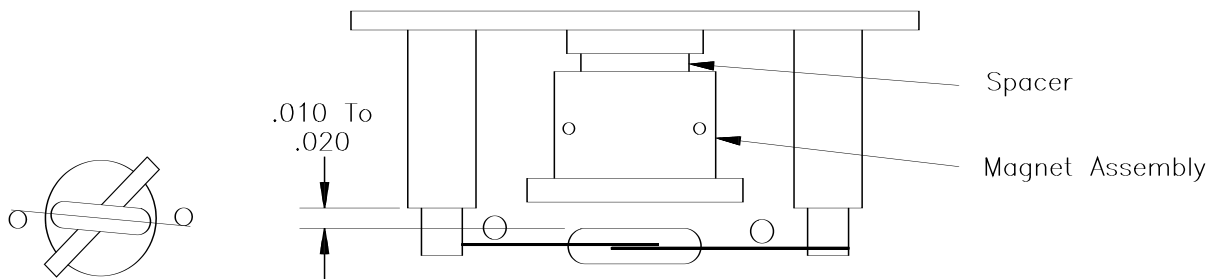


FIGURE C-1. Reed switch assembly

C.2 Bearing Replacement Procedure

The bearings used in the 014A sensor are special stainless steel ball bearings with a protective shield. Bearings are lubricated and sealed. **DO NOT LUBRICATE BEARINGS AS THE LUBRICATION WILL ATTRACT DUST AND INHIBIT BEARING OPERATION.**

- A. Follow steps A, B, and C in reed switch replacement procedures.
- B. Loosen set screws in magnet assembly, lift shaft and collar up and out of bearing mount. Be sure to retain lower spacer.

- C. Insert a right-angle type of tool, such as an Allen wrench, into bearing. Cock it slightly to one side and remove both bearings.
- D. Install new bearings. Be careful not to introduce dirt particles into bearings. **CLEAN HANDS ONLY! DO NOT ADD LUBRICATION OF ANY KIND.**
- E. Reassemble the sensor in reverse order. Be sure to include spacers over the bearings when replacing the shaft in the bearing mount. After the magnet assembly has been tightened, a barely perceptible amount of endplay should be felt when the shaft is moved up and down.

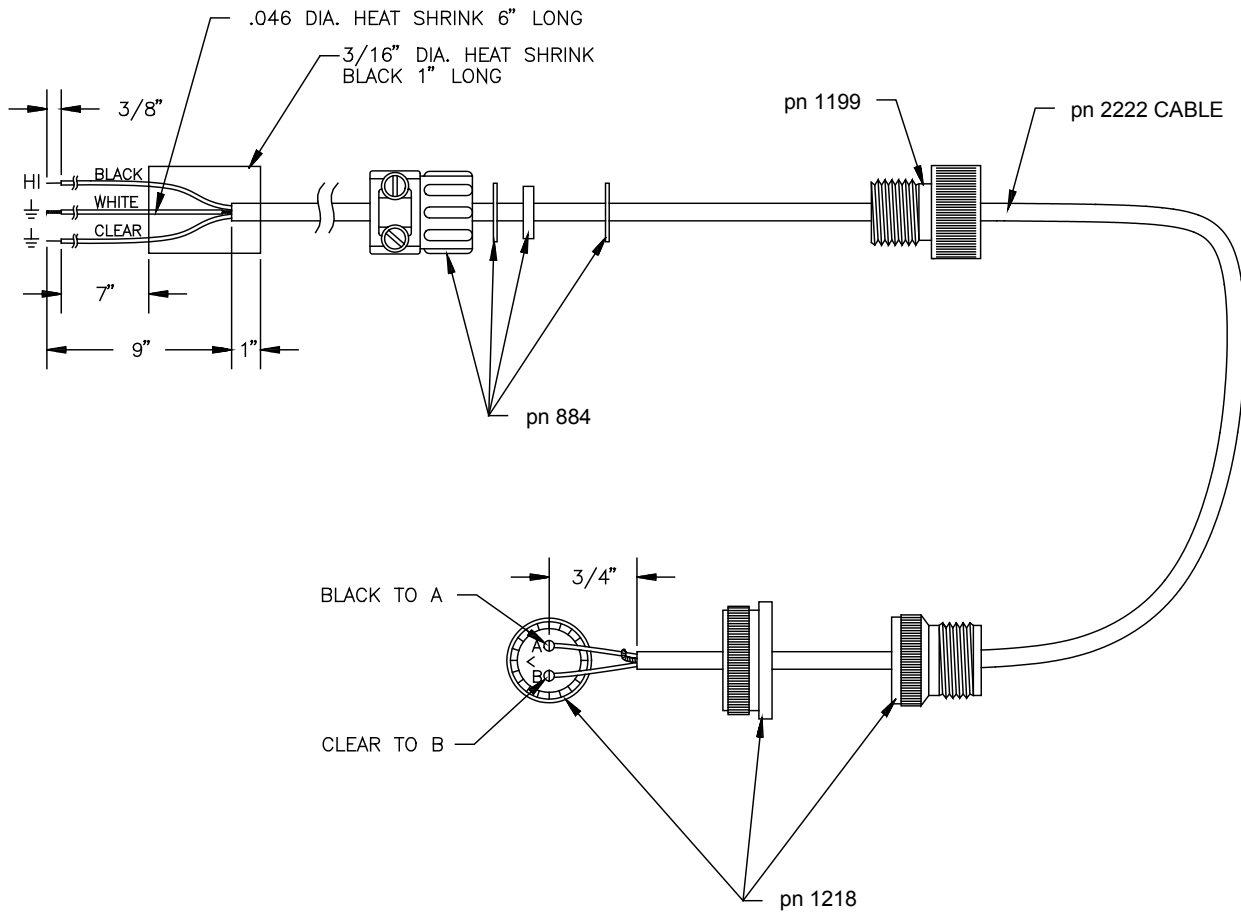


FIGURE C-2. Cable diagram

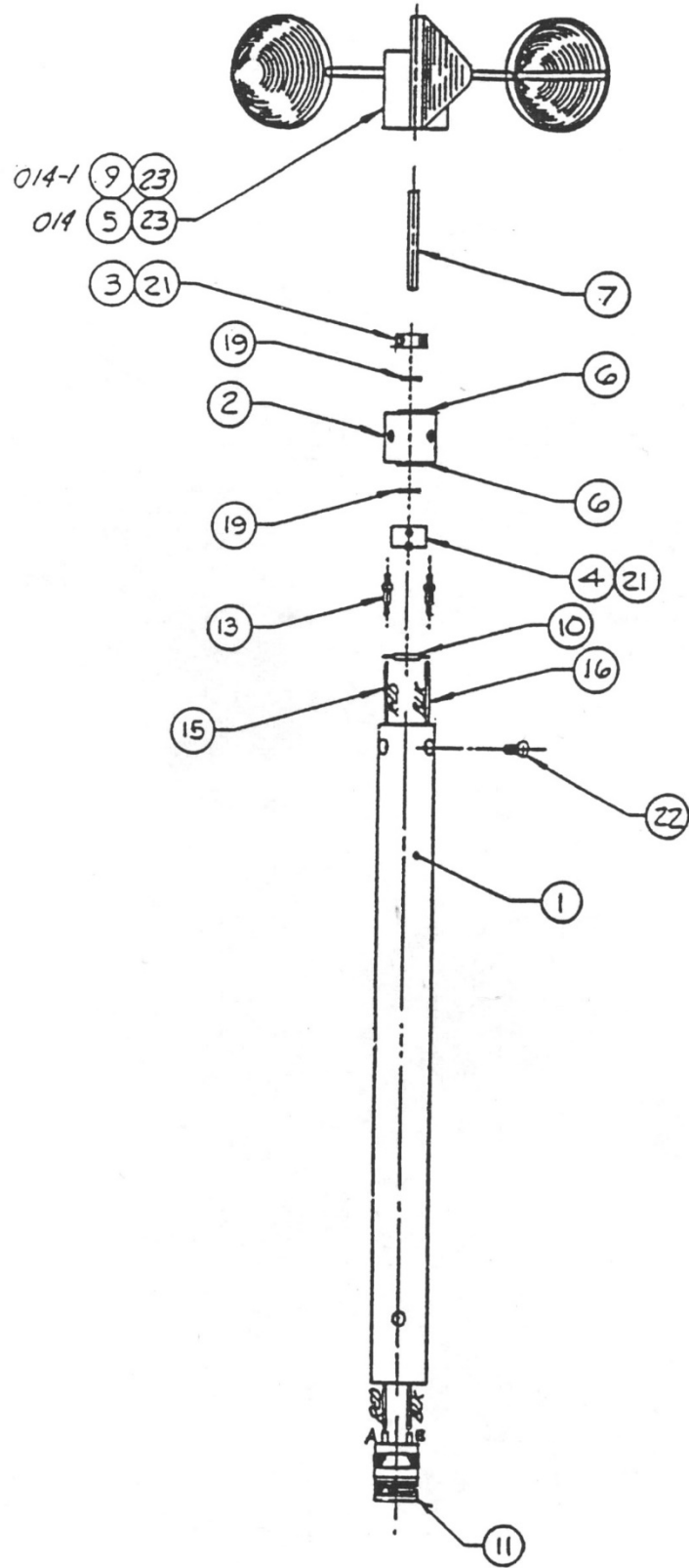


FIGURE C-3. Parts diagram

TABLE C-1. Met One Parts List

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<u>Item</u>	<u>Part No.</u>	<u>Description</u>	<u>Qty./Assy</u>
1	1011685-2	Housing	1
2	101685-4	Bearing Mount	1
3	101685-7	Collar	1
4	101715	Magnet Assembly	1
5	101812	Assy, Cup (Alum)	1
6	101898	Bearing	2
7	86001	Shaft	1
8	101048-2	Label	1
9	1812-1	Assy, Cup (Lexan)	1
10	880160	Switch, Reed	1
11	500295	Conn, 2 Pin Male	1
12	510020	Cap	1
13	970062	Terminal	2
14			
15	9980480	Wire, 22G Red	18"
16	980445	Wire, 22GA Black	18"
17			
18			
19	860250	Spacer	2
20			
21	601250	SCR, SET A/H C/P 4-40x1/8	4
22	601230	SCR,FLT HD PHIL 4-40x1/4	3
23	601680	SCR,SET A/H C/P 8-23x3/8	2
24			
25	995120	Adhesive, (RTV 108)	A/R
26	995100	Adhesive, Epoxy (907)	A/R
27	995425	Locite 222-21	A/R
28	995060	Adhesive, Silicone	5 ml
29	995430	Locite 290-21	A/R
30	400010	Cable, 2 Cond.	REF
31	500372	Conn, 2 Pin Socket	REF
32	480500	Clamp	REF

Appendix D. Theory of Operation

D.1 Mechanical

The sensor's cup assembly consists of three aluminum cups mounted on a cup assembly hub. A stainless steel shaft, which rotates on precision-sealed ball bearings, connects the cup assembly to a magnet assembly. When the shaft is rotated, the turning magnet assembly causes a reed switch to close. There are two contacts (reed switch closures) per revolution. The frequency of closures is linear from threshold to 45 m s⁻¹.

D.2 Calibration

The 014A sensor has a threshold speed of 0.447 m s⁻¹ and follows the equation:

$$V = 0.447 + f/1.250 \text{ where}$$

V = wind speed (m s⁻¹), and
f = output frequency (hz.)

or, $V = 1.0 + f/0.5589$
where V = wind speed (mph), and
f = output frequency (hz.)

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